

Work-In-Progress: Video Analytics From Edge To Server



Jiashen Cao, Ramyad Hadidi, Joy Arulraj, Hyesoon Kim





Motivation

- Camera systems generate massive amount of data nowadays.
 - According to Lucid Motors, 6 12 cameras are able to produce 60 400 MB data per second.
 - It is no longer possible to analyze large-scale data by hands.
- The advancements in deep neural networks encourage engineers to use it to understand data without manual efforts.
- In a system, more devices (cameras, sensors) are deployed on the edge.
 - More computation resources are available on the edge.
 - Edge devices are usually under-utilized in the system.





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 Deep Neural Networks based System
 Processes Real-Time Inference On The Edge
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Challenges

- Deep neural networks inferences are compute intensive.
 - ▶ VGG-16 model has 16 GFLOPs.
- Each edge device has limited computation resource.
 - A Nvidia TX2 development board.
 - □ 2 GHz ARM CPU processor and a low end GPU.
- As results,
 - Limited computation resource causes longer latency.





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Observation

- In video analytics system, not all requests have the same accuracy requirements.
 - To identify the license plate number of a vehicle, the system needs to run deep neural network prediction with high accuracy.
 - To estimate number of cars passing a traffic intersection, the system requires lower accuracy support.



Opportunities exist to leverage accuracy and improve the performance.





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Our Approach

- A Multi-Stage Neural Network.
 - Support multiple accuracy requirements in a single model.
 - Stop in the middle of inference if accuracy requirements are met.
- Conduct case study on VGG-16.





Our Approach (cont'd)

- Multi-Stage VGG-16 properties.
 - Add customized fully connected layers to shallow convolution layers.
 - Inferences stop early if accuracy requirements are met.





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Preliminary Results



Early Stop Layer #

